



Study of feasibility of image-based localization

Meyer Reda

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This book is on localization with visualization. He speak about how visualization is needed on a robot to get his localization with. For better result, a precise calibration is needed. It's a better way to calculate the localization with a fix camera on the robot than out of the robot, it's simplifying the measurement process. I advice this book to all engineers which are looking for a first step into localization with visualization.

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